arXiv:1008.1086v2 [math.PR] 6 Sep 2012

GLOBAL SOLUTIONS OF THE RANDOM VORTEX FILAMENT EQUATION

Z. BRZEŹNIAK[†], M. GUBINELLI[‡] AND M. NEKLYUDOV[†]

ABSTRACT. In this article we prove existence of a global solution for the random vortex filament equation. Our work gives a positive answer to a question left open in recent publications: Berselli and Gubinelli [5] showed the existence of global solution for a smooth initial condition while Bessaih, Gubinelli, Russo [6] proved the existence of a local solution for a general initial condition.

In this article we prove the existence of a global solution for the following random vortex filament equation

$$\frac{d\gamma}{dt} = u^{\gamma(t)}(\gamma(t)), \quad t \in [0,T] \tag{0.1}$$

$$\gamma(0) = \gamma_0, \tag{0.2}$$

where the initial condition γ_0 is a geometric ν-rough path (for some $\nu \in (\frac{1}{3}, 1)$), see Assumption 2.7. Here $\gamma : [0,T] \to \mathcal{D}_{\gamma_0} \subset \mathcal{C}$ is some trajectory in the subset $\mathcal{D}_{\gamma_0}$ of $\mathcal{C}$ of continuous closed curves in $\mathbb{R}^3$, u^Y, $Y \in \mathcal{D}_{\gamma_0} \subset \mathcal{C}$ is a vector field given by

$$u^Y(x) = \int_Y \nabla\phi(x-y) \times dy. \tag{0.3}$$

where $\phi : \mathbb{R}^3 \to \mathbb{R}$ is a smooth function which satisfies certain assumptions (see Hypothesis 3.1). Exact meaning of the line integral above and set $\mathcal{D}_{\gamma_0}$ we consider will be explained below. This equation appear in fluid dynamics in the theory of three dimensional Euler equations. It is well known that for two dimensional Euler equations vorticity $\vec{\omega} = \operatorname{curl} \vec{u}$ is transported along the flow of the liquid. The situation changes drastically in three dimensional case. Additional "stretching" term in the equation defining vorticity leads to possibility of blow up of the vorticity. Furthermore, result of Beale, Kato, and Majda [2] suggest that possible singularity of Euler equations appear when vorticity field of fluid blows up. Consequently, understanding of the behaviour of vorticity of ideal fluid is one of the most important problems in fluid dynamics.

The properties of the motion of the vorticity has been studied for the last 150 years starting from the works of Helmholtz [22] and Kelvin [23]. It has been suggested by Kelvin to use Biot-Savart law

$$\vec{u}(x) = \int \frac{\vec{x}-\vec{y}}{|\vec{x}-\vec{y}|^3} \times \vec{\omega}(\vec{y}) d\vec{y}, x, y \in \mathbb{R}^3$$

Date: December 4, 2019.

combined with assumption that vorticity is supported by some smooth curve γ

$$\omega(\vec{x},t)=\Gamma\int\limits_0^1\delta(\vec{x}-\gamma(s,t))\frac{\partial\gamma(s,t)}{\partial s}ds, x\in\mathbb{R}^3, t\geq 0$$

and definition of the flow

$$\left\{\begin{array}{lcl}\frac{d\vec{X}_t(\vec{x})}{dt} &=& \vec{u}(\vec{X}_t(\vec{x}),t),\ \ t\geq 0,\\ \vec{X}_0(\vec{x}) &=& \vec{x}.\end{array}\right. \tag{0.4}$$

to formally deduce the filament equation

$$\frac{\partial\gamma}{\partial t}(s,t)=-\frac{\Gamma}{4\pi}\int\limits_0^1\frac{\gamma(s,t)-\gamma(r,t)}{|\gamma(s,t)-\gamma(r,t)|^3}\times\frac{\partial\gamma(r,t)}{\partial r}dr. \tag{0.5}$$

The assumption that vorticity is supported by some curve is coherent with numerical simulations of 3D turbulent fluids which show that regions where vorticity is big have a form of "filament", see, for instance [3], [29].

The equation (0.5) has singularity when r is close to s and initial curve γ is smooth. As a consequence, the energy of the solution of this equation given by formula

$$E(t)=\frac{\Gamma^2}{8\pi}\int\limits_0^1\int\limits_0^1\frac{1}{|\gamma(s,t)-\gamma(r,t)|}\frac{\partial\gamma(r,t)}{\partial r}\cdot\frac{\partial\gamma(s,t)}{\partial s}dsdr, t\geq 0$$

is infinite for any smooth curve $\gamma(\cdot,t)$. Hence different methods are employed to avoid singularity. For instance, Gallavotti [18] motivated by finiteness of the energy integral for Brownian Motion[1], considers non smooth initial curves γ_0. Rosenhead [28] has suggested to use the following model

$$\frac{\partial\gamma}{\partial t}(s,t)=-\frac{\Gamma}{4\pi}\int\limits_0^1\frac{\gamma(s,t)-\gamma(r,t)}{(|\gamma(s,t)-\gamma(r,t)|^2+\mu^2)^{3/2}}\times\frac{\partial\gamma(r,t)}{\partial r}dr. \tag{0.6}$$

The equation ((0.1)-(0.3)) has been studied by Berselli and Bessaih [4] and then by Berselli and Gubinelli [5]. It contains equation (0.6) considered by Rosenhead as a very particular case when

$$\phi(\vec{x})=\frac{\Gamma}{(|\vec{x}|^2+\mu^2)^{1/2}}, \vec{x}\in\mathbb{R}^3, \mu>0.$$

Eq. (0.1) is really a nonlinear PDE for a function $\gamma:[0,T]\times[0,1]\to\mathbb{R}^3$. The natural setting to have a well-posed Cauchy problem is obtained by requiring that the vector field u is well defined and Lipshitz in the space variable. To this effect the approach followed in [4] is to set up the equation as an evolution problem in the Sobolev space H^1 of closed curves in $\mathbb{R}^3$ with square integrable first derivative (with respect to the parameter). This approach implies that the vector field (once lifted to H^1) does not allow good estimates to have global existence. This is ultimately due to the fact that in $3d$ incompressible flows vortices strech and undergo a complex dynamics and that a priori this could lead to a explosion of the H^1 norm. Such a difficulty should be compared to the more stable behavior of

[1] defined as double stochastic integral

2d vortex points which, under incompressible flows, are simply transported along the flow lines. Exploiting the conservation of the kinetic energy of the flow and a control of the velocity field generated by the vortex line via the associated kinetic energy Berselli and Gubinelli [5] showed the existence of global solution to equation (0.1) with initial conditions in H^1. After that Bessaih, Gubinelli, Russo [6], partly motivated by the random filament models suggested by Gallavotti [18] and by Chorin [12], considered the above evolution problem when the initial condition is a random closed curve which for definiteness, in the above paper, has been taken to be the sample of a Brownian loop (a Brownian motion starting at $0 \in \mathbb{R}^3$ and conditioned to return to $0 \in \mathbb{R}^3$ at time 1). In this case it is no more possible to set up the problem in H^1 since Brownian trajectories almost surely do not belong to this space. A more serious problem is the meaning to give to the generalized Biot-Savart relation (0.3) since the line integral along a Brownian trajectory is a notoriously difficult object to define. Stochastic integration (à la Itô or Stratonovich) does not provide a good framework to study this problem and [6] identified the natural setting to have a well posed problem by considering the evolution as an equation on the space of rough paths.

Rough path theory has been introduced by T. J. Lyons in the seminal paper [25] (see also [17, 26, 27]) as a way to overcome certain difficulties of stochastic integration theories and have a robust analytical framework to solve stochastic differential equations and similar problems involving integration of non-regular vector-fields. It turns out that rough paths theory and in particular the notion of *controlled paths* introduced in [20] allows to give a natural interpretation to the Biot-Savart relation (0.3) and obtain a well-posed problem. Using this approach Bessaih, Gubinelli, Russo [6] could obtain existence of a local solution to equation (0.1) when initial condition is a closed curve of Hölder class with exponent $\nu \in (\frac{1}{3}, 1]$ (suitably lifted to rough path space).

The aim of the present paper is to extend the energy method of Berselli and Gubinelli to the rough path setting to obtain global existence of solution of the equation (0.1) when the initial condition is a (geometric) rough path, thus completing the analysis of [6].

Recently there have been some progress in the study of evolution equations in the space of (controlled) rough paths. In particular Hairer [21] showed how to use rough path theory to have well-posedness of a multidimensional Burgers type equation driven by additive space-time white noise. The key technical tool to obtain these results has been the observation that the non-linear term in the Burgers equation has the same structure of the Biot-Savart relation (0.3) and thus can be similarly handled via rough paths techniques.

1. NOTATION

In this section we present the controlled path framework introduced by Gubinelli [20]. Let V be a fixed Banach space. We define the following two objects:

$$\begin{aligned} C_n(V) &= \{f \in C((S^1)^n, V) : \ f(t,t,\dots,t) = 0, t \in S^1\}, \\ C_*(V) &= \bigcup_{k\in\mathbb{N}} C_k(V). \end{aligned}$$

The operator

$$\begin{aligned} \delta &: C_n(V) \to C_{n+1}(V), \\ (\delta g)(t_1,\dots,t_{n+1}) &= \sum_{i=1}^{n+1}(-1)^i g(t_1,\dots \hat{t_i} \dots, t_{n+1}), n \in \mathbb{N} \end{aligned}$$

satisfies the following fundamental property

$$\delta\delta = 0,$$

where $\delta\delta$ is understood as an operator from $C_n(V)$ to $C_{n+2}(V)$. Thus δ induces a complex and we can denote

$$\begin{aligned} \mathcal{Z}C_k(V) &= C_k(V) \cap \ker \delta, \\ \mathcal{B}C_k(V) &= C_k(V) \cap \operatorname{im} \delta. \end{aligned}$$

To avoid confusion we will use notation δ_n for operator $\delta : C_n(V) \to C_{n+1}(V)$. Furthermore, it can be noticed that

$$\operatorname{im} \delta_n = \ker \delta_{n+1},$$

i.e. $\mathcal{Z}C_{k+1}(V) = \mathcal{B}C_k(V)$.

We will mainly consider the cases $n = 1$ and $n = 2$. Then operator δ has following form

$$\delta_1 g(t,s) = g(t) - g(s), \delta_2 h(t,u,s) = h(t,s) - h(t,u) - h(u,s), t,u,s \in S^1.$$

and we will use special topology in spaces $C_2(V)$ and $C_3(V)$. Let

$$\begin{aligned} |f|_\mu &= \sup_{a,b\in S^1} \frac{|f(a,b)|_V}{|a-b|^\mu}, \quad f \in C_2(V), \\ C_2^\mu(V) &= \{f \in C_2(V) : |f|_\mu < \infty\} \\ |g|_{\rho,\mu} &= \sup_{a,b,c\in S^1} \frac{|g(a,b,c)|_V}{|a-b|^\rho |b-c|^\mu}, \quad g \in C_3(V), \\ C_3^{\rho,\mu}(V) &= \{f \in C_3(V) : |f|_{\rho,\mu} < \infty\}, \\ C_3^\mu(V) &= \{f \in C_3(V) : f = \sum_i h_i, |f|_\mu = \sum_i |h_i|_{\rho_i,\mu-\rho_i} < \infty, \rho_i \in (0,\mu)\}, \\ \mathcal{Z}C_3^\mu(V) &= C_3^\mu(V) \cap \mathcal{Z}C_3(V), \\ \mathcal{Z}C_3^{1+}(V) &= \bigcup_{\mu>1} \mathcal{Z}C_3^\mu(V), \\ C_2^{1+}(V) &= \bigcup_{\mu>1} C_2^\mu(V). \end{aligned}$$

Then following fundamental proposition has been proved in [20]:

Proposition 1.1. *There exists an unique linear map $\Lambda : \mathcal{Z}C_3^{1+}(V) \to C_2^{1+}(V)$ such that*

$$\delta\Lambda = \mathrm{id}_{\mathcal{Z}C_3^{1+}(V)}.$$

Furthermore, for any $\mu > 1$, this map is continuous from $\mathcal{Z}C_3^\mu(V)$ to $C_2^\mu(V)$ and we have

$$\|\Lambda h\|_\mu \le \frac{1}{2^\mu - 2}\|h\|_\mu, h \in \mathcal{Z}C_3^{1+}(V).$$

Now, we define class of paths for which rough path integral will be defined.

Definition 1.2. *Let us fix $X \in C^\nu(S^1, V)$. We say that path $Y \in C(S^1, V)$ is weakly controlled by X if there exist functions $Z \in C^\nu(S^1, L(V, V))$ and $R \in C_2^{2\nu}(V)$ such that*

$$Y(\xi) - Y(\eta) = Z(\eta)(X(\xi) - X(\eta)) + R(\xi, \eta), \xi, \eta \in S^1, \tag{1.1}$$

Let $\mathcal{D}_X$ be the set of pairs (Y, Z), where $Y \in C(S^1, V)$ is a path weakly controlled by X, and $Z \in C^\nu(S^1, L(V, V))$ is such that $R \in C_2^{2\nu}(V)$, where R is defined by representation (1.1). We notice that this is vector space. Define the semi-norm in $\mathcal{D}_X$ as follows

$$\|(Y, Z)\|_{\mathcal{D}_X} = |Z|_{C^\nu} + \|R\|_{C_2^{2\nu}}, \tag{1.2}$$

where

$$R(\xi, \eta) = Y(\xi) - Y(\eta) - Z(\eta)(X(\xi) - X(\eta)), \xi, \eta \in S^1. \tag{1.3}$$

Furthermore, define the following norm

$$\|(Y, Z)\|^*_{\mathcal{D}_X} = \|Y\|_{\mathcal{D}_X} + |Y|_{C(S^1,V)}. \tag{1.4}$$

Then, one can prove that $(\mathcal{D}_X, \|\cdot\|^*_{\mathcal{D}_X})$ is a Banach space. From now on we will denote elements of $\mathcal{D}_X$ by (Y, Y') and the corresponding R will be denoted by R^Y. We will often omit to specify Y' when it is clear from the context and write $\|Y\|_{\mathcal{D}_X}$ instead of $\|(Y, Y')\|_{\mathcal{D}_X}$.

2. Definition and Properties of Rough Path integrals

In this section we define rough path integral and state some of its properties. We mainly follow [20] and [6].

Definition 2.1. *Let $\Pi : \mathcal{D}_X \ni (Y, Z) \mapsto Y \in C(S^1, \mathbb{R}^3)$ be the natural projection.*

We will need following properties of $\mathcal{D}_X$, see [20].

Lemma 2.2. $\Pi(\mathcal{D}_X) \subset C^\nu(S^1, \mathbb{R}^3)$.

Proof of Lemma 2.2. Immediately follows from inequality

$$\|Y\|_{C^\nu} \le \|Y\|^*_{\mathcal{D}_X}(1 + \|X\|_{C^\nu}). \tag{2.1}$$

□

Lemma 2.3. *Let $\phi \in C^2(\mathbb{R}^3, \mathbb{R}^3)$ and $(Y, Z) \in \mathcal{D}_X$. Then*

$$(W, W') := (\phi(Y), \phi'(Y)Z) \in \mathcal{D}_X \tag{2.2}$$

and the remainder has the following representation

$$R^W(\xi, \eta) = \phi'(Y(\xi))R(\xi, \eta) + (Y(\eta) - Y(\xi))$$

$$+ \int_0^1 [\nabla\phi(Y(\xi) + r(Y(\eta) - Y(\xi))) - \nabla\phi(Y(\xi))]dr, \xi, \eta \in S^1. \tag{2.3}$$

where R is the remainder for Y w.r.t. X given by (1.3)*. Furthermore, there exists a constant $K \ge 1$ such that*

$$\|\phi(Y)\|_{\mathcal{D}_X} \le K\|\nabla\phi\|_{C^1}\|Y\|_{\mathcal{D}_X}(1 + \|Y\|_{\mathcal{D}_X})(1 + \|X\|_{C^\nu})^2. \tag{2.4}$$

Moreover, if $(\tilde{Y}, \tilde{Z}) \in \mathcal{D}_{\tilde{X}}$ and

$$(\tilde{W}, \tilde{W}') := (\phi(\tilde{Y}), \phi'(\tilde{Y})\tilde{Z})$$

then

$$|W'-\tilde W'|_{C^\nu}+|R^W-R^{\tilde W}|_{C_2^{2\nu}}+|W-\tilde W|_{C^\nu}\le C(|X-\tilde X|_{C^\nu}+|Y'-\tilde Y'|_{C^\nu}+|R^Y-R^{\tilde Y}|_{C_2^{2\nu}}+|Y-\tilde Y|_{C^\nu}) \tag{2.5}$$

with

$$C=K\|\phi\|_{C^3}(1+\|X\|_{C^\nu}+\|\tilde X\|_{C^\nu})^3|(1+\|Y\|_{\mathcal{D}_X}+\|\tilde Y\|_{\mathcal{D}_{\tilde X}})^2. \tag{2.6}$$

In the case $X=\tilde X$ we have

$$\begin{aligned}\|\phi(Y)-\phi(\tilde Y)\|_{\mathcal{D}_X}\le& K\|\nabla\phi\|_{C^2}\|Y\|_{\mathcal{D}_X}\\ &(1+\|Y\|_{\mathcal{D}_X}+\|\tilde Y\|_{\mathcal{D}_X})^2(1+\|X\|_{C^\nu})^4\|Y-\tilde Y\|_{\mathcal{D}_X}.\end{aligned} \tag{2.7}$$

Proof of Lemma 2.3. See [20], Proposition 4 for all statements of the Lemma, except (2.3) (which is actually also proven, though not stated explicitly). Let us show (2.3). Denote $y(r)=Y(\xi)+r(Y(\eta)-Y(\xi)), r\in[0,1]$. Then

$$\begin{aligned}\phi(y(1))-\phi(y(0)) &= \int_0^1\phi'(y(r))y'(r)dr \qquad (2.8)\\ &= \sum_k(Y^k(\eta)-Y^k(\xi))\int_0^1\frac{\partial\phi}{\partial x_k}(y(r))dr\\ &= \sum_k\frac{\partial\phi}{\partial x_k}(Y(\xi))(Y^k(\eta)-Y^k(\xi))\\ &+ \sum_k(Y^k(\eta)-Y^k(\xi))\int_0^1[\frac{\partial\phi}{\partial x_k}(y(r))-\frac{\partial\phi}{\partial x_k}(Y(\xi))]dr\\ &= \sum_{k,l}\frac{\partial\phi}{\partial x_k}(Y(\xi))(Y')^{kl}(X^l(\eta)-X^l(\xi))+\sum_k\frac{\partial\phi}{\partial x_k}(Y(\xi))(R^Y)^k(\xi,\eta)\\ &+ \sum_k(Y^k(\eta)-Y^k(\xi))\int_0^1[\frac{\partial\phi}{\partial x_k}(y(r))-\frac{\partial\phi}{\partial x_k}(Y(\xi))]dr,\end{aligned}$$

and the result follows. □

Now we define integral of path Y weakly controlled by X w.r.t. another path Z, weakly controlled by X. We will need one more definition.

Definition 2.4. *Let $\nu>\frac13$. We say that couple $\mathbb{X}=(X,\mathbb{X}^2)$, $X\in C^\nu(S^1,\mathbb{R}^3)$, $\mathbb{X}^2\in C_2^{2\nu}(L(\mathbb{R}^3,\mathbb{R}^3))$ is a ν-rough path if the following condition is satisfied:*

$$\mathbb{X}^2(\xi,\rho)-\mathbb{X}^2(\xi,\eta)-\mathbb{X}^2(\eta,\rho)=(X(\xi)-X(\eta))\otimes(X(\eta)-X(\rho)),\xi,\eta,\rho\in S^1 \tag{2.9}$$

Remark 2.5. If $\nu>1$ and $\mathbb{X}$ is a ν-rough path, then $\mathbb{X}$ is identically pair of constants $(X(0),0)$. Indeed, in this case X is Hölder function with exponent more than 1 i.e. constant $X(0)$. Hence, $\mathbb{X}^2=0$.

Remark 2.6. If $\nu \in (\frac{1}{2}, 1]$ then $\mathbb{X}^2$, the second component of a ν-rough path $\mathbb{X} = (X, \mathbb{X}^2)$, is uniquely determined by its first component. Indeed,

$$\mathbb{X}^{2,ij}(\xi,\eta) = \int_\xi^\eta (X^i_\rho - X^i_\eta) dX^j_\rho, \xi, \eta \in S^1, i, j = 1, 2, 3 \tag{2.10}$$

where the integral is understood in the sense of Young, see [30]. One can show that $\mathbb{X}^2$ defined by formula (2.10) satisfies conditions of Definition 2.4. Let us show uniqueness of $\mathbb{X}^2$. Assume that there exists another $\mathbb{X}^2_1$ which satisfies definition 2.4. Put $G(\xi) = \mathbb{X}^2(\xi, 0) - \mathbb{X}^2_1(\xi, 0)$. Then by condition 2.9

$$\mathbb{X}^2(\xi,\rho) - \mathbb{X}^2_1(\xi,\rho) = G(\xi) - G(\rho),$$

and, since $\mathbb{X}^2 \in C^{2\nu}_2$, G is a Hölder function of order bigger than 1. Hence, $G = 0$. Therefore, $\mathbb{X}^2_1 = \mathbb{X}^2$.

Note that by identity (2.9) it follows that $\mathbb{X}^2(\xi, \xi) = 0, \xi \in S^1$.

Assumption 2.7. *We say that our ν-rough path $(X, \mathbb{X}^2)$ is an geometric ν-rough path if there exist a sequence $(X_n, \mathbb{X}^2_n)$ such that*

$$X_n \in C^\infty(S^1, \mathbb{R}^3),$$

$$\mathbb{X}^{2,ij}_n(\xi,\eta) = \int_\xi^\eta (X^i_n(\rho) - X^i_n(\eta)) dX^j_n(\rho), \xi, \eta \in S^1, i, j = 1, 2, 3,$$

and

$$\lim_{n\to\infty} \left[|X_n - X|_{C^\nu} + |\mathbb{X}^2_n - \mathbb{X}^2|_{C^{2\nu}_2}\right] = 0. \tag{2.11}$$

Example 2.8. Let $\{B_t\}_{t\in[0,1]}$ be standard three dimensional Brownian bridge such that $B_0 = B_1 = x_0$ and let $\mathbb{B}^{2,ij}$ be the area process

$$\mathbb{B}^{2,ij}(\xi,\eta) = \int_\xi^\eta (B^i_\rho - B^i_\eta) dB^j_\rho, i, j = 1, 2, 3$$

where the integral can be understood either in the Stratonovich or in the Itô sense. Then, this couple $(B, \mathbb{B}^2)$ is a ν-rough path see [6, p.1849]. Moreover, if the integral is understood in Stratonovich sense it is geometric ν-rough path. Indeed, it follows from Theorem 3.1 in [16] that we can approximate X with piecewise linear dyadic X'_n in the sense of assumption 2.7a.s..

From now on we suppose that the geometric ν-rough path $\mathbb{X} = (X, \mathbb{X}^2)$ and the corresponding Banach space $\mathcal{D}_X$ are fixed.

Lemma 2.9. *Let $\pi = \{\xi_0 = \xi < \xi_1 < \ldots < \xi_n = \eta\}$ be a finite partition of $[\xi, \eta]$ and $d(\pi) = \sup_i |\xi_{i+1} - \xi_i|$ is a mesh of π. If $Y, Z \in \mathcal{D}_X$ then the limit*

$$\lim_{d(\pi)\to 0} \sum_{i=0}^{n-1} [Y(\xi_i)(Z(\xi_{i+1}) - Z(\xi_i)) + Y'(\xi_i)Z'(\xi_i)\mathbb{X}^2(\xi_{i+1}, \xi_i)] \tag{2.12}$$

exists and is denoted by definition by

$$\int_{\xi}^{\eta} Y dZ.$$

Proof of Lemma 2.9. See [20], Theorem 1. □

Remark 2.10. In the case of $\nu > \frac{1}{2}$ the line integral defined in the Lemma 2.9 is reduced to the Young definition of the line integral $\int Y dZ$. Indeed, it is enough to notice that second term in formula (2.12) is of the order $O(|\xi_{i+1} - \xi_i|^{2\nu})$, $2\nu > 1$. Obviously, line integral does not depend upon Y', Z' in this case.

Lemma 2.11. *Assume $Y, W \in \mathcal{D}_X$, $\tilde{Y}, \tilde{W} \in \mathcal{D}_{\tilde{X}}$. Define maps $Q, \tilde{Q} : (S^1)^2 \to \mathbb{R}$ by the following identities*

(2.13)

$$Q(\eta,\xi) := \int_{\xi}^{\eta} Y dW - Y(\xi)(W(\eta) - W(\xi)) - Y'(\xi)W'(\xi)\mathbb{X}^2(\eta,\xi), \eta, \xi \in S^1,$$

(2.14)

$$\tilde{Q}(\eta,\xi) := \int_{\xi}^{\eta} \tilde{Y} d\tilde{W} - \tilde{Y}(\xi)(\tilde{W}(\eta) - \tilde{W}(\xi)) - \tilde{Y}'(\xi)\tilde{W}'(\xi)\tilde{\mathbb{X}}^2(\eta,\xi), \eta, \xi \in S^1.$$

Then $Q, \tilde{Q} \in C_2^{3\nu}$.
Moreover, there exists constant $C = C(\nu) > 0$ such that for all $Y, W \in \mathcal{D}_X$

$$\|Q\|_{C_2^{3\nu}} \leq C(1 + \|X\|_{C^\nu} + \|\mathbb{X}^2\|_{C_2^{2\nu}})\|Y\|_{\mathcal{D}_X}\|W\|_{\mathcal{D}_X}. \tag{2.15}$$

Furthermore,

$$\begin{aligned}\|Q - \tilde{Q}\|_{C_2^{3\nu}} &\leq C(1 + \|X\|_{C^\nu} + \|\mathbb{X}^2\|_{C_2^{2\nu}}) \\ &\quad ((\|Y\|_{\mathcal{D}_X} + \|\tilde{Y}\|_{\mathcal{D}_{\tilde{X}}})\varepsilon_W + (\|W\|_{\mathcal{D}_X} + \|\tilde{W}\|_{\mathcal{D}_{\tilde{X}}})\varepsilon_Y + \varepsilon_X).\end{aligned} \tag{2.16}$$

where

$$\varepsilon_Y = |Y' - \tilde{Y}'|_{C^\nu} + |R^Y - R^{\tilde{Y}}|_{C_2^{2\nu}} + |Y - \tilde{Y}|_{C^\nu},$$

$$\varepsilon_W = |W' - \tilde{W}'|_{C^\nu} + |R^W - R^{\tilde{W}}|_{C_2^{2\nu}} + |W - \tilde{W}|_{C^\nu},$$

$$\varepsilon_X = (\|Y\|_{\mathcal{D}_X} + \|\tilde{Y}\|_{\mathcal{D}_{\tilde{X}}})(\|W\|_{\mathcal{D}_X} + \|\tilde{W}\|_{\mathcal{D}_{\tilde{X}}})(|X - \tilde{X}|_{C^\nu} + |\mathbb{X}^2 - \tilde{\mathbb{X}}^2|_{C_2^{2\nu}}).$$

Proof of Lemma 2.11. See [20], Theorem 1. For formula (2.16) see [20], p.104, formula (27). □

By Lemmata 2.9 and 2.3 for any $A \in C^2(\mathbb{R}^3, L(\mathbb{R}^3, \mathbb{R}^3)), Y \in \mathcal{D}_X$ we can a define a map $V^Y : \mathbb{R}^3 \to \mathbb{R}$ by invoking rough path integral as follows

$$V^Y(x) := \int_{S^1} A(x - Y)dY, x \in \mathbb{R}^3. \tag{2.17}$$

We have following bounds on its regularity:

Lemma 2.12. *Let $Y \in \mathcal{D}_X$, $\tilde{Y} \in \mathcal{D}_{\tilde{X}}$, then there exists $C_1 = C_1(\nu), C_2 = C_2(\mathbb{X})$ such that for any integer $n \geq 0$,*

$$\|\nabla^n V^Y\|_{L^\infty} \leq 4C_1C_2^3\|\nabla^{n+1}A\|_{C^1}\|Y\|_{\mathcal{D}_X}^2(1+\|Y\|_{\mathcal{D}_X}) \tag{2.18}$$

and

$$\|\nabla^n V^Y - \nabla^n V^{\tilde{Y}}\|_{L^\infty} \leq C(\nu)|A|_{C^{n+3}}C_X^4(1+\|Y\|_{\mathcal{D}_X}+\|\tilde{Y}\|_{\mathcal{D}_{\tilde{X}}})^3 \tag{2.19}$$
$$(|X-\tilde{X}|_{C^\nu}+|\mathbb{X}^2-\tilde{\mathbb{X}}^2|_{C_2^{2\nu}}+|Y'-\tilde{Y}'|_{C^\nu}+|R^Y-R^{\tilde{Y}}|_{C_2^{2\nu}}+|Y-\tilde{Y}|_{C^\nu}),$$

where

$$C_X = 1+|X|_{C^\nu}+|\tilde{X}|_{C^\nu}+|\mathbb{X}^2|_{C_2^{2\nu}}+|\tilde{\mathbb{X}}^2|_{C_2^{2\nu}}.$$

In the case of $X = \tilde{X}$, inequality (2.19) *can be rewritten as*

$$\|\nabla^n V^Y - \nabla^n V^{\tilde{Y}}\|_{L^\infty} \leq 16C_1C_2^3\|\nabla^{n+1}A\|_{C^2}\|Y\|_{\mathcal{D}_X}(1+\|Y\|_{\mathcal{D}_X})^2\|Y-\tilde{Y}\|_{\mathcal{D}_X}^*. \tag{2.20}$$

Proof of Lemma 2.12. Inequalities (2.18) and (2.20) were proved in [6], Lemma 7. Now we will show (2.19). It is enough to consider the case of $n = 0$. By formulae (2.15) and (2.14) we have

$$\begin{aligned} V^Y - V^{\tilde{Y}}(x) &= A(x-Y(0))(Y(1)-Y(0)) \\ &- A(x-\tilde{Y}(0))(\tilde{Y}(1)-\tilde{Y}(0)) \\ &+ (A(x-Y))'(0)Y'(0)\mathbb{X}^2(0,1) \\ &- (A(x-\tilde{Y}))'(0)\tilde{Y}'(0)\tilde{\mathbb{X}}^2(0,1) \\ &+ Q^x(0,1)-\tilde{Q}^x(0,1) \end{aligned}$$

where Q^x and $\tilde{Q}^x$ (given by formulae (2.15) and (2.14)) satisfy inequality (2.16) and we have identified S^1 with $[0,1]$. Therefore, $Y(1) = Y(0)$, $\tilde{Y}(1) = \tilde{Y}(0)$. Hence, we have

$$\begin{aligned} |V^Y - V^{\tilde{Y}}|_{L^\infty} \leq \sup_x |(A(x-Y))'(0)Y'(0)\mathbb{X}^2(0,1) - (A(x-\tilde{Y}))'(0)\tilde{Y}'(0)\tilde{\mathbb{X}}^2(0,1)| \\ + \sup_x |Q^x(0,1)-\tilde{Q}^x(0,1)|. \end{aligned} \tag{2.21}$$

For the first term on the r.h.s. we have

$$\begin{aligned} &|(A(x-Y))'(0)Y'(0)\mathbb{X}^2(0,1) - (A(x-\tilde{Y}))'(0)\tilde{Y}'(0)\tilde{\mathbb{X}}^2(0,1)| \\ &\leq |(dA(x-Y(0))Y'(0)Y'(0) - dA(x-\tilde{Y}(0))\tilde{Y}'(0)\tilde{Y}'(0))\mathbb{X}^2(0,1)| \\ &+ |dA(x-\tilde{Y}(0))\tilde{Y}'(0)\tilde{Y}'(0)(\mathbb{X}^2(0,1)-\tilde{\mathbb{X}}^2(0,1))| \\ &\leq |\mathbb{X}^2|_{C_2^{2\nu}}|dA(x-Y(0))Y'(0)Y'(0) - dA(x-\tilde{Y}(0))\tilde{Y}'(0)\tilde{Y}'(0)| \\ &+ |A|_{C^2}|Y'|_{L^\infty}^2|\mathbb{X}^2-\tilde{\mathbb{X}}^2|_{C_2^{2\nu}} \\ &\leq |\mathbb{X}^2|_{C_2^{2\nu}}|Y'|_{L^\infty}^2|A|_{C^2}|Y'-\tilde{Y}'|_{L^\infty} + |\mathbb{X}^2|_{C_2^{2\nu}}|A|_{C^1}(|Y'|_{L^\infty}+|\tilde{Y}'|_{L^\infty})|Y'-\tilde{Y}'|_{L^\infty} \\ &+ |A|_{C^2}|Y'|_{L^\infty}^2|\mathbb{X}^2-\tilde{\mathbb{X}}^2|_{C_2^{2\nu}}. \end{aligned} \tag{2.22}$$

By (2.16) we can estimate second term as follows

$$|Q^x-\tilde{Q}^x|_{C_2^{3\nu}}\leq C\Big[(\|A(x-Y)\|_{\mathcal{D}_X}+\|A(x-\tilde{Y})\|_{\mathcal{D}_{\tilde{X}}})\varepsilon_Y + (\|Y\|_{\mathcal{D}_X}+\|\tilde{Y}\|_{\mathcal{D}_{\tilde{X}}})\varepsilon_A+\varepsilon_X\Big].$$

where

$$\begin{aligned}\varepsilon_Y&=|Y-\tilde{Y}|_{C^\nu}+|Y'-\tilde{Y}'|_{C^\nu}+|R^Y-R^{\tilde{Y}}|_{C_2^{2\nu}},\\ \varepsilon_A&=|A(x-Y)-A(x-\tilde{Y})|_{C^\nu}+|A(x-Y)'-A(x-\tilde{Y})'|_{C^\nu}\\ &\quad+|R^{A(x-Y)}-R^{A(x-\tilde{Y})}|_{C_2^{2\nu}},\\ \varepsilon_X&=(\|A(x-Y)\|_{\mathcal{D}_X}+\|A(x-\tilde{Y})\|_{\mathcal{D}_{\tilde{X}}})\\ &\quad\times(\|Y\|_{\mathcal{D}_X}+\|\tilde{Y}\|_{\mathcal{D}_{\tilde{X}}})(|X-\tilde{X}|_{C^\nu}+|\mathbb{X}^2-\tilde{\mathbb{X}}^2|_{C_2^{2\nu}}).\end{aligned}$$

By formula (2.5) we can estimate ε_A as follows

$$\begin{aligned}|\varepsilon_A|&\leq K|A|_{C^3}(1+|X|_{C^\nu}+|\tilde{X}|_{C^\nu})^3(1+|Y|_{D_X}+|\tilde{Y}|_{D_{\tilde{X}}})^2\\ &\quad\times(|X-\tilde{X}|_{C^\nu}+|Y-\tilde{Y}|_{C^\nu}+|Y'-\tilde{Y}'|_{C^\nu}+|R^Y-R^{\tilde{Y}}|_{C_2^{2\nu}}).\end{aligned}\tag{2.23}$$

By inequality (2.4) we infer that

$$\|A(x-Y)\|_{\mathcal{D}_X}\leq K|A|_{C^2}|Y|_{D_X}(1+|Y|_{D_X})(1+|X|_{C^\nu})^2,\tag{2.24}$$

and similarly,

$$\|A(x-\tilde{Y})\|_{\mathcal{D}_{\tilde{X}}}\leq K|A|_{C^2}|\tilde{Y}|_{D_{\tilde{X}}}(1+|\tilde{Y}|_{D_{\tilde{X}}})(1+|\tilde{X}|_{C^\nu})^2.\tag{2.25}$$

Therefore, combining (2.23) with (2.23), (2.24) and (2.25) we get

$$\begin{aligned}&|Q^x-\tilde{Q}^x|_{C_2^{3\nu}}\leq C(\nu)|A|_{C^{n+3}}(1+|X|_{C^\nu}+|\tilde{X}|_{C^\nu})^4(1+\|Y\|_{\mathcal{D}_X}+\|\tilde{Y}\|_{\mathcal{D}_{\tilde{X}}})^3\\ &(|X-\tilde{X}|_{C^\nu}+|\mathbb{X}^2-\tilde{\mathbb{X}}^2|_{C_2^{2\nu}}+|Y'-\tilde{Y}'|_{C^\nu}+|R^Y-R^{\tilde{Y}}|_{C_2^{2\nu}}+|Y-\tilde{Y}|_{C^\nu}).\end{aligned}\tag{2.26}$$

Hence, the result follows from (2.22) and (2.26). □

We will denote for any $Y\in\mathcal{D}_X$, $\tilde{Y}\in\mathcal{D}_{\tilde{X}}$

$$|Y-\tilde{Y}|_D=|X-\tilde{X}|_{C^\nu}+|\mathbb{X}^2-\tilde{\mathbb{X}}^2|_{C_2^{2\nu}}+|Y'-\tilde{Y}'|_{C^\nu}+|R^Y-R^{\tilde{Y}}|_{C_2^{2\nu}}+|Y-\tilde{Y}|_{C^\nu}.$$

3. Random Filaments evolution problem

Let $\mathcal{D}_{\mathbb{X},T}=C([0,T],\mathcal{D}_X)$ be a vector space with the usual supremum norm

$$|F|_{\mathcal{D}_{\mathbb{X},T}}=\sup_{t\in[0,T]}|F(t)|^*_{\mathcal{D}_X}.\tag{3.1}$$

Obviously $\mathcal{D}_{\mathbb{X},T}$ is a Banach space. Assume also that the function ϕ appeared in the formula (0.3) satisfies following hypothesis.

Hypothesis 3.1.(i) $\phi:\mathbb{R}^3\to\mathbb{R}$ *is even function.*
(ii) *the Fourier transform of* ϕ *is real and non-negative function:*

$$\hat{\phi}(k)\geq 0,\quad k\in\mathbb{R}^3$$

(iii)

$$\int_{\mathbb{R}^3} (1+|k|^2)^2 \hat{\phi}(k) dk < \infty$$

Example 3.2. The function $\phi = \phi_\mu$, $\mu > 0$ defined by

$$\phi(\cdot) = \frac{\Gamma}{(|\cdot|^2 + \mu^2)^{1/2}}$$

is smooth and satisfies hypothesis 3.1, see p.6 of [5].

Then the following local existence and uniqueness Theorem for problem (0.1)-(0.3) has been proved in [6], see Theorem 3,p.1842.

Theorem 3.3. *Assume $\phi \in C^6(\mathbb{R}^3, \mathbb{R})$, $\nu \in (\frac{1}{3}, 1)$, $\mathbb{X} = (X, \mathbb{X}^2)$ is a ν-rough path, $\gamma_0 \in \mathcal{D}_X$. Then there exists a time $T_0 = T_0(\nu, |\phi|_{C^5}, \mathbb{X}) > 0$ such that the problem* (0.1)-(0.3) *has unique solution in $\mathcal{D}_{\gamma_\nu, T_0} \subset \mathcal{D}_{\mathbb{X}, T_0}$.*

Our aim is to prove global existence of solution of the problem (0.1)-(0.3) under assumptions of Theorem 3.3 and additional hypothesis 3.1 i.e. we shall prove

Theorem 3.4. *Assume that $T > 0$, γ_0 is a geometric ν-rough path, $\phi \in C^6(\mathbb{R}^3, \mathbb{R})$ satisfies satisfies Hypothesis 3.1 and $\nu \in (\frac{1}{3}, 1)$. Then the problem* (0.1)-(0.3) *has unique solution in $\mathcal{D}_{\gamma_0, T}$.*

We will need the following definition.

Definition 3.5. *Let $\phi \in C^4(\mathbb{R}^3, \mathbb{R})$, $\gamma \in \mathcal{D}_X$. Put*

$$\mathcal{H}_X^\phi(\gamma) = \frac{1}{2} \int_{S^1} \vec{\psi}^\gamma(\gamma(\xi)) \cdot d\vec{\gamma}(\xi), \tag{3.2}$$

where

$$\vec{\psi}^\gamma(x) = \int_{S^1} \phi(x - \gamma(\eta)) d\vec{\gamma}(\eta).$$

$\mathcal{H}_X^\phi(\gamma)$ is called the energy of path γ. We will omit ϕ below.

Remark 3.6. Definition (3.2)-(3.5) is well posed. Indeed, by Lemma 2.12 $\vec{\psi}^\gamma \in C^2(\mathbb{R}^3, \mathbb{R}^3)$ and, therefore, it follows by Lemma 2.3 that $\vec{\psi}^\gamma(\gamma(\cdot)) \in \mathcal{D}_X$.

Remark 3.7. Assume that $\nu > \frac{1}{2}$ and $\gamma \in C^1(S^1, \mathbb{R}^3)$. Then by Remark 2.10 the line integrals in the definition of energy are understood in the sense of Young and

$$\mathcal{H}_X(\gamma) = \frac{1}{2} \int_{S^1} \int_{S^1} \phi(\vec{\gamma}(\xi) - \vec{\gamma}(\eta)) (\frac{d\vec{\gamma}}{d\xi}(\xi), \frac{d\vec{\gamma}}{d\eta}(\eta)) d\xi d\eta. \tag{3.3}$$

Lemma 3.8. *Assume $\phi \in C^4(\mathbb{R}^3, \mathbb{R})$. Then there exists constant $C = C(\nu, \mathbb{X})$ such that for all $\gamma \in \mathcal{D}_X$*

$$|\mathcal{H}_X(\gamma)| \le C |\phi|_{C^4} |\gamma|_{\mathcal{D}_X}^4 (1 + |\gamma|_{\mathcal{D}_X})^2. \tag{3.4}$$

Moreover, the map $\mathcal{H}_X : \mathcal{D}_X \to \mathbb{R}$ is locally Lipshitz i.e. for any $R > 0$ there exists $C = C(R)$ such that for any $\gamma, \tilde{\gamma} \in \mathcal{D}_X$, $|\gamma|_{\mathcal{D}_X} < R$, $|\tilde{\gamma}|_{\mathcal{D}_X} < R$ we have

$$|\mathcal{H}_X(\gamma) - \mathcal{H}_X(\tilde{\gamma})| \le C(R) |\gamma - \tilde{\gamma}|_{\mathcal{D}_X}^*. \tag{3.5}$$

Furthermore, for any $R > 0$ there exists $C = C(R)$ such that for any $\gamma \in \mathcal{D}_X$, $\tilde\gamma \in \mathcal{D}_{\tilde X}$,

$$|\gamma|_{\mathcal{D}_X} < R, |\tilde\gamma|_{\mathcal{D}_{\tilde X}} < R,$$

$$C_{X,\tilde X} = |X|_{C^\nu} + |\tilde X|_{C^\nu} + |\mathbb{X}^2|_{C_2^{2\nu}} + |\tilde{\mathbb{X}}^2|_{C_2^{2\nu}} < R$$

we have

(3.6)
$$|\mathcal{H}_X(\gamma) - \mathcal{H}_{\tilde X}(\tilde\gamma)| \le C(R)(|X-\tilde X|_{C^\nu} + |\mathbb{X}^2 - \tilde{\mathbb{X}}^2|_{C_2^{2\nu}} + |\gamma-\tilde\gamma|_{C^\nu} + |\gamma'-\tilde\gamma'|_{C^\nu} + |R^\gamma - R^{\tilde\gamma}|_{C_2^{2\nu}}).$$

Proof of Lemma 3.8. First we will show inequality (3.4). By representation (2.13) we have

$$\begin{aligned}\mathcal{H}_X(\gamma) &= \frac{1}{2}(\vec\psi^\gamma(\gamma(0))(\vec\gamma(1) - \vec\gamma(0))) \\ &\quad + \left[d\vec\psi^\gamma(\gamma(0))\gamma'(0)\right]\gamma'(0)\mathbb{X}^2(1,0) + Q(0,1) \\ &= I + II + III, \gamma \in \mathcal{D}_X.\end{aligned}$$

Since $\vec\gamma(1) = \vec\gamma(0)$ we infer that $I = 0$. Concerning the second term by Lemma 2.12 we have the following estimate

$$\begin{aligned}|II| &\le \|\mathbb{X}^2\|_{C_2^{2\nu}} \|\nabla\vec\psi\|_{L^\infty} |\gamma'|^2_{L^\infty} \\ &\le C(\nu, \mathbb{X})|\phi|_{C^3}|\gamma|^4_{\mathcal{D}_X}(1 + |\gamma|_{\mathcal{D}_X}).\end{aligned} \tag{3.7}$$

For third term we infer from inequality (2.15)

$$|III| \le \|Q\|_{C_2^{3\nu}} \le C(\nu, \mathbb{X})|\vec\psi(\vec\gamma)|_{\mathcal{D}_X}|\vec\gamma|_{\mathcal{D}_X}. \tag{3.8}$$

Then by Lemmas 2.3 and 2.12 we have

$$\begin{aligned}|\vec\psi^\gamma(\vec\gamma)|_{\mathcal{D}_X} &\le C(\nu, \mathbb{X})|\psi^\gamma|_{C^2}|\vec\gamma|_{\mathcal{D}_X}(1 + |\vec\gamma|_{\mathcal{D}_X}) \\ &\le C(\nu, \mathbb{X})|\phi|_{C^4}|\vec\gamma|^3_{\mathcal{D}_X}(1 + |\vec\gamma|_{\mathcal{D}_X})^2\end{aligned} \tag{3.9}$$

Combining (3.7), (3.8) and (3.9) we get inequality (3.4).

Now we will prove inequality (3.6). By formula (2.14) we have

$$\begin{aligned}\mathcal{H}_X(\gamma) - \mathcal{H}_{\tilde X}(\tilde\gamma) &= \frac{1}{2}\Big[(\nabla\psi^\gamma(\gamma(0))\gamma'(0)\gamma'(0) - \nabla\psi^{\tilde\gamma}(\tilde\gamma(0))\tilde\gamma'(0)\tilde\gamma'(0))\mathbb{X}^2(1,0) \\ &\quad + \nabla\psi^{\tilde\gamma}(\tilde\gamma(0))\tilde\gamma'(0)\tilde\gamma'(0)(\mathbb{X}^2(1,0) - \tilde{\mathbb{X}}^2(1,0)) + Q(0,1) - \tilde Q(0,1)\Big] \\ &= I + II + III\end{aligned} \tag{3.10}$$

The first term in (3.10) can be represented as follows

$$\begin{aligned}I &= (\nabla\psi^\gamma(\gamma(0))\gamma'(0)\gamma'(0) - \nabla\psi^{\tilde\gamma}(\tilde\gamma(0))\tilde\gamma'(0)\tilde\gamma'(0))\mathbb{X}^2(1,0) \\ &= \big[(\nabla\psi^\gamma(\gamma(0)) - \nabla\psi^{\tilde\gamma}(\tilde\gamma(0)))\gamma'(0)\gamma'(0) \\ &+ \nabla\psi^{\tilde\gamma}(\tilde\gamma(0))(\gamma'(0) - \tilde\gamma(0))\gamma'(0) \\ &+ \nabla\psi^{\tilde\gamma}(\tilde\gamma(0))\tilde\gamma(0)(\gamma'(0) - \tilde\gamma(0))\big]\,\mathbb{X}^2(1,0) = A + B + C\end{aligned} \tag{3.11}$$

The first term in (3.11) can be estimated as follows

$$
\begin{aligned}
|A| &= |(\nabla\psi^{\gamma}(\gamma(0)) - \nabla\psi^{\tilde{\gamma}}(\tilde{\gamma}(0)))\gamma'(0)\gamma'(0)\mathbb{X}^2(1,0)| \\
&\leq \|\mathbb{X}^2\|_{C_2^{2\nu}}|\gamma|^2_{\mathcal{D}_X}(|\nabla\psi^{\gamma}(\gamma(0)) \\
&- \nabla\psi^{\gamma}(\tilde{\gamma}(0))| + |\nabla\psi^{\gamma}(\tilde{\gamma}(0)) - \nabla\psi^{\tilde{\gamma}}(\tilde{\gamma}(0))|) \\
&\leq \|\mathbb{X}^2\|_{C_2^{2\nu}}|\gamma|^2_{\mathcal{D}_X}(|\psi^{\gamma}|_{C^2}|\gamma(0) \\
&- \tilde{\gamma}(0)| + C_X^4|\phi|_{C^4}(1 + |\gamma|_{\mathcal{D}_X} + |\tilde{\gamma}|_{\mathcal{D}_{\tilde{X}}})^3|\gamma - \tilde{\gamma}|_D \\
&\leq KC_X^4|\phi|_{C^4}(1 + |\gamma|_{\mathcal{D}_X} + |\tilde{\gamma}|_{\mathcal{D}_{\tilde{X}}})^3|\gamma - \tilde{\gamma}|_D,
\end{aligned} \tag{3.12}
$$

where second inequality follows from inequality (2.19) and third one from inequality (2.18). For second term we have by inequality (2.18)

$$
\begin{aligned}
|B| &\leq C\|\mathbb{X}^2\|_{C_2^{2\nu}}|\gamma|_{\mathcal{D}_X}|\phi|_{C^3}|\tilde{\gamma}|^2_{\mathcal{D}_X}(1 + |\tilde{\gamma}|_{\mathcal{D}_X})|\gamma - \tilde{\gamma}|_D \\
&\leq CC_X(1 + |\gamma|_{\mathcal{D}_X} + |\tilde{\gamma}|_{\mathcal{D}_{\tilde{X}}})^3|\gamma - \tilde{\gamma}|_D.
\end{aligned} \tag{3.13}
$$

Similarly, we have for third term

$$
|C| \leq C(\nu, \mathbb{X}, |\gamma|_{\mathcal{D}_X}, |\tilde{\gamma}|_{\mathcal{D}_X})|\gamma - \tilde{\gamma}|_D. \tag{3.14}
$$

Term II in (3.10) can be estimated as follows

$$
\begin{aligned}
|II| &\leq |\nabla\psi^{\tilde{\gamma}}|_{L^\infty}|\tilde{\gamma}|^2_{\mathcal{D}_X}|\gamma - \tilde{\gamma}|_D \\
&\leq C_X^3|\phi|_{C^3}(1 + |\gamma|_{\mathcal{D}_X} + |\tilde{\gamma}|_{\mathcal{D}_{\tilde{X}}})^3|\gamma - \tilde{\gamma}|_D.
\end{aligned}
$$

Thus it remains to estimate third term of equality (3.10). We have by inequality (2.16)

$$
\begin{aligned}
|Q(0,1) - \tilde{Q}(0,1)| &\leq \|Q - \tilde{Q}\|_{C_2^{3\nu}} \\
&\leq C_X\Big[(|\psi^{\tilde{\gamma}}(\tilde{\gamma})|_{\mathcal{D}_{\tilde{X}}} + |\psi^{\gamma}(\gamma)|_{\mathcal{D}_X})|\gamma - \tilde{\gamma}|_D \\
&+ (|\tilde{\gamma}|_{\mathcal{D}_{\tilde{X}}} + |\tilde{\gamma}|_{\mathcal{D}_{\tilde{X}}})|\psi^{\tilde{\gamma}}(\tilde{\gamma}) - \psi^{\gamma}(\gamma)|_D \\
&+ (|\psi^{\tilde{\gamma}}(\tilde{\gamma})|_{\mathcal{D}_{\tilde{X}}} + |\psi^{\gamma}(\gamma)|_{\mathcal{D}_X})(|\tilde{\gamma}|_{\mathcal{D}_{\tilde{X}}} + |\tilde{\gamma}|_{\mathcal{D}_{\tilde{X}}}) \\
&\times (|X - \tilde{X}|_{C^\nu} + |\mathbb{X}^2 - \tilde{\mathbb{X}}^2|_{C_2^{2\nu}})\Big]
\end{aligned}
$$

Term $|\psi^{\tilde{\gamma}}(\tilde{\gamma})|_{\mathcal{D}_X}$ is bounded by the constant $C = C(\nu, \mathbb{X}, |\tilde{\gamma}|_{\mathcal{D}_X})$ by inequality (2.18). Therefore, to prove estimate (3.5) it is enough to show that there exists constant $C = C(\nu, \mathbb{X}, R)$ such that for $\gamma, \tilde{\gamma} \in \mathcal{D}_X$ with $|\gamma|_{\mathcal{D}_X}, |\tilde{\gamma}|_{\mathcal{D}_X} \leq R$

$$
|\psi^{\tilde{\gamma}}(\tilde{\gamma}) - \psi^{\gamma}(\gamma)|_D \leq C|\tilde{\gamma} - \gamma|_D. \tag{3.15}
$$

By triangle inequality we have

$$
\begin{aligned}
|\psi^{\tilde{\gamma}}(\tilde{\gamma}) - \psi^{\gamma}(\gamma)|_D &\leq |\psi^{\tilde{\gamma}}(\tilde{\gamma}) - \psi^{\tilde{\gamma}}(\gamma)|_D + |\psi^{\tilde{\gamma}}(\gamma) - \psi^{\gamma}(\gamma)|_D \\
&= I + II.
\end{aligned} \tag{3.16}
$$

The first term can be estimated using inequality (2.5) as follows

$$
|I| \leq KC_X^3|\psi^{\tilde{\gamma}}|_{C^3}(1 + |\tilde{\gamma}|_{\mathcal{D}_{\tilde{X}}} + |\gamma|_{\mathcal{D}_X})^2|\tilde{\gamma} - \gamma|_D. \tag{3.17}
$$

By inequality (2.18) we have

$$
|\psi^{\tilde{\gamma}}|_{C^3} \leq C|\phi|_{C^5}|\tilde{\gamma}|^2_{\mathcal{D}_X}(1 + |\tilde{\gamma}|_{\mathcal{D}_X}) \tag{3.18}
$$

Combining (3.17) and (3.18) we get necessary estimate for I. It remains to find an estimate for term II. By inequalities (2.4) and (2.20) we have

$$\begin{aligned} II &= |\psi^{\tilde\gamma}(\gamma) - \psi^{\gamma}(\gamma)|_D \\ &\le (1+|X|_\nu)|\psi^{\tilde\gamma}(\gamma) - \psi^{\gamma}(\gamma)|_{\mathcal{D}_X} \\ &\le K|\nabla\psi^{\tilde\gamma} - \nabla\psi^{\gamma}|_{C^1}|\gamma|_{\mathcal{D}_X}(1+|\gamma|_{\mathcal{D}_X})(1+|X|_\nu)^3 \\ &\le K|\phi|_{C^5}C_X^7(1+|\gamma|_{\mathcal{D}_X}+|\tilde\gamma|_{\mathcal{D}_{\tilde X}})^5|\tilde\gamma-\gamma|_D. \end{aligned} \tag{3.19}$$

Hence the inequality (3.6) follows. Inequality (3.5) is a consequence of inequality (3.6). □

Corollary 3.9. *Under assumptions of Lemma 3.8 and assumption 2.7 energy $\mathcal{H}_X : \mathcal{D}_X \to \mathbb{R}$ is a continuous function on $\mathcal{D}_X$. Furthermore, for any $\gamma \in \mathcal{D}_X$*

$$0 \le \mathcal{H}_X(\gamma) < \infty.$$

Proof of Corollary 3.9. We only need to show that $\mathcal{H}_X(\gamma) \ge 0$, for any $\gamma \in \mathcal{D}_X$. Other statements of the Corollary easily follow from Lemma 3.8. Fix $n \in \mathbb{N}$. Let $C(0) = \cup_{i=1}^{n^6} C(k_i)^n$ be a partition of the cube $C(0)$ with center 0 and length n^2 on the cubes $C(k_i)^n$ of the length of $\frac{1}{n}$ with centers k_i and nonintersecting interiors. Define $\hat\phi^n(k) = \hat\phi(k_i)$, $k \in C(k_i)^n$ and 0 otherwise. Consequently, define

$$\phi^n(x) = \sum_{i=1}^{n^6} \hat\phi(k_i) \int\limits_{C(k_i)^n} e^{i<k,x>} dk, x \in \mathbb{R}^3$$

Then $\phi = \lim\limits_{n\to\infty} \phi^n$ in C^4 norm because of the assumption 3.1. Consequently,

$$\mathcal{H}_X^{\phi}(\gamma) = \lim_{n\to\infty} \mathcal{H}_X^{\phi_n}(\gamma). \tag{3.20}$$

Now formula

$$\mathcal{H}_X^{z}(\gamma) = \frac{1}{(2\pi)^3} \int\limits_{\mathbb{R}^3} \hat z(k) \Big| \int\limits_{S^1} e^{i(k,\gamma_s)} d\gamma_s \Big|^2 dk, \gamma \in \mathcal{D}_X. \tag{3.21}$$

is correct for $z = \phi_n$, because ϕ^n is a sum of a finite number of Fourier modes. Therefore,

$$\mathcal{H}_X^{\phi_n}(\gamma) \ge 0. \tag{3.22}$$

Thus, the result follows from identity (3.20) and inequality (3.22). □

Now we are going to show that energy is a local integral of motion for problem (0.1)-(0.3).

Lemma 3.10. *Let $\gamma \in \mathcal{D}_{\gamma_0,T_0}$ be a local solution of problem* (0.1)-(0.3) *(such solution exists by Theorem 3.3). Then*

$$\frac{d\mathcal{H}_{\gamma_0}(\gamma(s))}{ds} = 0, s \in [0, T_0).$$

Proof of Lemma 3.10. Since $\gamma(0) = \gamma_0 \in \mathcal{D}_{\gamma_0}$ is a geometric rough path there exist sequence $\{\gamma_0^n\}_{n=1}^{\infty} \in C^\infty(S^1, \mathbb{R}^3)$ such that

$$|\gamma_0^n - \gamma_0|_{C^\nu} + |\gamma^2 - \gamma^2|_{C_2^{2\nu}} \to 0, n \to \infty.$$

Now $\gamma_0^n \in \mathcal{D}_{\gamma_0^n}$, $\gamma_0 \in \mathcal{D}_{\gamma_0}$. Thus we can put $(\gamma_0^n)' = (\gamma_0)' = 1$ and $R^{\gamma_0^n} = R^{\gamma_0} = 0$. Hence we deduce that

$$|\gamma_0^n - \gamma_0|_D \to 0, n \to \infty.$$

Denote $\gamma^n \in C([0,\infty), \mathbf{H}^1(S^1, \mathbb{R}^3))$ the global solution of problem (0.1)-(0.3) with initial condition γ_0^n. Existence of such solution has been proved in Theorem 2 of [5]. Then according to [5] (Theorem 4, p.1846) we have

$$\sup_{t\in[0,T_0]} |\gamma^n(t) - \gamma(t)|_D \to 0, n \to \infty.$$

Therefore, by continuity of energy functional $\mathcal{H}_{\gamma_0}$ we have

$$\mathcal{H}_{\gamma_0}(\gamma(s)) = \lim_{n\to\infty} \mathcal{H}_{\gamma_0^n}(\gamma^n(s)), s \in [0, T_0]. \tag{3.23}$$

Furthermore, by Lemma 2 of [5], we have

$$\mathcal{H}_{\gamma_0^n}(\gamma^n(s)) = \mathcal{H}_{\gamma_0^n}(\gamma_0^n), s \in [0, T_0]. \tag{3.24}$$

As a result, combining (3.23) and (3.24) we get statement of the Lemma. □

Let us recall definition of along with ν-rough path Y

$$u^Y(x) = \int_Y \nabla\phi(x-y) \times dy, Y \in \mathcal{D}_X. \tag{3.25}$$

Now we show that if energy functional of Y is bounded then associated velocity is a smooth function. We have

Lemma 3.11 (See Lemma 3 in [5])**.** *For any $n \in \mathbb{Z}, n \geq 0$, we have following bound*

$$\|\nabla^n u^\gamma\|_{L^\infty} \leq \frac{1}{(2\pi)^{3/2}} \left[\int_{\mathbb{R}^3} |\vec{k}|^{2(1+n)} \hat{\phi}(\vec{k}) d\vec{k}\right]^{1/2} \mathcal{H}_X^{1/2}(\gamma), \gamma \in \mathcal{D}_X, \tag{3.26}$$

provided that the integral $\int_{\mathbb{R}^3} |\vec{k}|^{2(1+n)} \hat{\phi}(\vec{k}) d\vec{k}$ is finite and $\phi \in C^{n+4}(\mathbb{R}^3, \mathbb{R}^3)$.

Proof of Lemma 3.11. For smooth γ Lemma has been proved in [5] Lemma 3. In general case, when $\gamma \in \mathcal{D}_X$, it is enough to notice that both sides of inequality (3.26) are locally Lipshitz and therefore, continuous w.r.t. distance $d(Y, \tilde{Y}) := |Y - \tilde{Y}|_D$, $Y \in \mathcal{D}_X$, $\tilde{Y} \in \mathcal{D}_{\tilde{X}}$. Indeed, continuity of $\mathcal{H}_X$ has been proven in Lemma 3.8 and continuity of $\|\nabla^n u^\gamma\|_{L^\infty}$ follows from Lemma 2.12. □

Now we are ready to prove Theorem 3.4.

Proof of Theorem 3.4. According to Theorem 3.3 there exists unique local solution of problem (0.1)-(0.3). Then, we can find $T^* > 0$ such that there exists unique maximal local solution $\gamma : [0, T^*) \to \mathcal{D}_{\gamma_0}$ and

$$\lim_{t\uparrow T^*} \|\gamma(t)\|_{\mathcal{D}_{\gamma_0}} = \infty, \tag{3.27}$$

see e.g. [11]. Notice that we will have

$$\frac{d\mathcal{H}_{\gamma_0}(\gamma(s))}{ds} = 0, s \in [0, T^*). \tag{3.28}$$

Indeed, by Theorem 3.3 for any $t_0 \in [0, T^*)$ there exists unique local solution $\tilde{\gamma}$ of problem (0.1), (0.3) with initial condition $\gamma(t_0)$ on segment $[t_0, t_0 + \varepsilon_{t_0}]$ for some $\varepsilon_{t_0} > 0$. Therefore, $\gamma = \tilde{\gamma}$ on the segment $[t_0, t_0 + \varepsilon_{t_0}]$. Hence,

$$\frac{d\mathcal{H}_{\gamma_0}(\gamma(s))}{ds} = 0, s \in [t_0, t_0 + \varepsilon_{t_0}], t_0 \in [0, T^*),$$

and identity (3.28) follows. We need to show that $T^* = \infty$. Therefore, it is enough to prove

$$\sup_{t\in[0,T^*)} \|\gamma(t)\|_{\mathcal{D}_{\gamma_0}} < \infty.$$

Indeed, by contradiction with (3.27), the result will follow. In the rest of the proof we show such estimate. We recall that

$$\gamma(t) = \gamma_0 + \int_0^t u^{\gamma(s)}(\gamma(s))ds. \tag{3.29}$$

Firstly we have

$$\begin{aligned} |\gamma(t)|_{L^\infty} &\le |\gamma_0|_{L^\infty} + \int_0^t |u^{\gamma(s)}|_{L^\infty} ds \\ &\le |\gamma_0|_{L^\infty} + C\int_0^t \mathcal{H}_{\gamma_0}(\gamma(s))ds \\ &\le |\gamma_0|_{L^\infty} + C\mathcal{H}_{\gamma_0}(\gamma_0)t, t \in [0, T^*). \end{aligned} \tag{3.30}$$

It follows from (3.29) that

$$\gamma'(t) = \gamma_0' + \int_0^t \nabla u^{\gamma(s)}(\gamma(s))\gamma'(s)ds, t \in [0, T^*). \tag{3.31}$$

Therefore, by Lemmas 3.10 and 3.11

$$\begin{aligned} |\gamma'(t)|_{L^\infty} &\le |\gamma_0'|_{L^\infty} + \int_0^t |\nabla u^{\gamma(s)}|_{L^\infty} |\gamma'(s)|_{L^\infty} ds \\ &\le |\gamma_0'|_{L^\infty} + \int_0^t C\mathcal{H}_{\gamma_0}^{1/2}(\gamma(s))|\gamma'(s)|_{L^\infty} ds \\ &= |\gamma_0'|_{L^\infty} + \int_0^t C\mathcal{H}_{\gamma_0}^{1/2}(\gamma_0)|\gamma'(s)|_{L^\infty} ds, t \in [0, T^*). \end{aligned} \tag{3.32}$$

Then by Gronwall inequality we infer our second estimate

$$|\gamma'(t)|_{L^\infty} \le |\gamma_0'|_{L^\infty} e^{C\mathcal{H}_{\gamma_0}^{1/2}(\gamma_0)t}, t \in [0, T^*). \tag{3.33}$$

We will need one auxiliary estimate. We have

$$\begin{aligned}
|\gamma(t)|_{C^\nu} &\le |\gamma_0|_{C^\nu} + \int_0^t |u^{\gamma(s)}(\gamma(s))|_{C^\nu}|ds \\
&\le |\gamma_0|_{C^\nu} + \int_0^t |\nabla u^{\gamma(s)}|_{L^\infty}|\gamma(s)|_{C^\nu} ds \\
&\le |\gamma_0|_{C^\nu} + \int_0^t C\mathcal{H}_{\gamma_0}^{1/2}(\gamma(s))|\gamma(s)|_{C^\nu} ds \\
&= |\gamma_0|_{C^\nu} + \int_0^t C\mathcal{H}_{\gamma_0}^{1/2}(\gamma_0)|\gamma(s)|_{C^\nu} ds, t \in [0, T^*). \qquad (3.34)
\end{aligned}$$

Thus, by Gronwall inequality we get

$$|\gamma(t)|_{C^\nu} \le |\gamma_0|_{C^\nu} e^{C\mathcal{H}_{\gamma_0}^{1/2}(\gamma_0)t}, t \in [0, T^*). \qquad (3.35)$$

Now we can estimate C^ν norm of γ'. We have

$$\begin{aligned}
|\gamma'(t)|_{C^\nu} &\le |\gamma_0'|_{C^\nu} + \int_0^t |\nabla u^{\gamma(s)}(\gamma(s))\gamma'(s)|_{C^\nu} ds \\
&\le |\gamma_0'|_{C^\nu} + \int_0^t (|\nabla u^{\gamma(s)}|_{L^\infty}|\gamma'(s)|_{C^\nu} + |\gamma'(s)|_{L^\infty}|\nabla u^{\gamma(s)}(\gamma(s))|_{C^\nu}) ds \\
&\le |\gamma_0'|_{C^\nu} + \int_0^t (|\nabla u^{\gamma(s)}|_{L^\infty}|\gamma'(s)|_{C^\nu} + |\gamma'(s)|_{L^\infty}|\nabla^2 u^{\gamma(s)}|_{L^\infty}|\gamma(s)|_{C^\nu}) ds \\
&\le |\gamma_0'|_{C^\nu} \\
&+ \int_0^t (C\mathcal{H}_{\gamma_0}^{1/2}(\gamma_0)(|\gamma'(s)|_{C^\nu} + |\gamma_0'|_{L^\infty}|\gamma_0|_{C^\nu} e^{C\mathcal{H}_{\gamma_0}(\gamma_0)s})) ds, t \in [0, T^*), \qquad (3.36)
\end{aligned}$$

where last inequality follows from Lemmas 3.10 and 3.11. Then by Gronwall inequality we get third estimate

$$|\gamma'(t)|_{C^\nu} \le (|\gamma_0'|_{C^\nu} + |\gamma_0'|_{L^\infty}|\gamma_0|_{C^\nu}) e^{C\mathcal{H}_{\gamma_0}(\gamma_0)t}, t \in [0, T^*). \qquad (3.37)$$

It remains to find an estimate for $|R^{\gamma(t)}|_{2\nu}$. We have

$$R^{\gamma(t)} = R^{\gamma_0} + \int_0^t R^{u^{\gamma(s)}(\gamma(s))} ds, t \in [0, T^*). \qquad (3.38)$$

By identity (2.3) we have for $s \in [0, T^*)$

$$R^{u^{\gamma(s)}(\gamma(s))}(\xi,\eta) = \nabla u^{\gamma(s)}(\gamma(s,\xi))R^{\gamma(s)}(\xi,\eta) + \sum_k (\gamma^k(s,\eta) - \gamma^k(s,\xi))\times$$

$$\int_0^1 \left[\frac{\partial u^{\gamma(s)}}{\partial x_k}(\gamma(s,\xi) + r(\gamma(s,\eta) - \gamma(s,\xi))) - \frac{\partial u^{\gamma(s)}}{\partial x_k}(\gamma(s,\xi)) \right] dr. \tag{3.39}$$

Therefore,

$$|R^{u^{\gamma(s)}(\gamma(s))}|_{\tilde{C}^{2\nu}} \le |\nabla u^{\gamma(s)}|_{L^\infty} |R^{\gamma(s)}|_{\tilde{C}^{2\nu}} + \frac{1}{2}|\gamma(s)|^2_{C^\nu} |\nabla^2 u^{\gamma(s)}|_{L^\infty}, s \in [0, T^*). \tag{3.40}$$

Thus, by inequalities (3.40) and (3.35) we have for $t \in [0, T^*)$

$$\begin{aligned} |R^{\gamma(t)}|_{\tilde{C}^{2\nu}} &\le |R^{\gamma_0}|_{\tilde{C}^{2\nu}} + \int_0^t (|\nabla u^{\gamma(s)}|_{L^\infty} |R^{\gamma(s)}|_{\tilde{C}^{2\nu}} + \frac{1}{2}|\gamma(s)|^2_{C^\nu} |\nabla^2 u^{\gamma(s)}|_{L^\infty}) ds \\ &\le |R^{\gamma_0}|_{\tilde{C}^{2\nu}} + \int_0^t (|\nabla u^{\gamma(s)}|_{L^\infty} |R^{\gamma(s)}|_{\tilde{C}^{2\nu}} + |\gamma_0|_{C^\nu} e^{C\mathcal{H}^{1/2}_{\gamma_0}(\gamma_0)t} |\nabla^2 u^{\gamma(s)}|_{L^\infty}) ds \\ &\le |R^{\gamma_0}|_{\tilde{C}^{2\nu}} + C(|\gamma_0|_{C^\nu}, \mathcal{H}_{\gamma_0}(\gamma_0)) e^{C\mathcal{H}^{1/2}_{\gamma_0}(\gamma_0)t} \\ &\quad + \int_0^t C\mathcal{H}^{1/2}_{\gamma_0}(\gamma_0) |R^{\gamma(s)}|_{\tilde{C}^{2\nu}} ds, \end{aligned} \tag{3.41}$$

where in the last inequality we used Lemmas 3.10 and 3.11. As the result, by Gronwall Lemma we get

$$|R^{\gamma(t)}|_{\tilde{C}^{2\nu}} \le (|R^{\gamma_0}|_{\tilde{C}^{2\nu}} + C(|\gamma_0|_{C^\nu}, \mathcal{H}_{\gamma_0}(\gamma_0)) e^{C\mathcal{H}^{1/2}_{\gamma_0}(\gamma_0)t})) e^{C\mathcal{H}^{1/2}_{\gamma_0}(\gamma_0)t}, t \in [0, T^*), \tag{3.42}$$

and combining estimates (3.30), (3.33), (3.37), and (3.42) we prove following a'priori estimate

$$|\gamma(t)|_{\mathcal{D}_{\gamma_0}} \le K(1 + \mathcal{H}_{\gamma_0}(\gamma_0))(1 + |\gamma_0|_{\mathcal{D}_{\gamma_0}}) |\gamma_0|_{\mathcal{D}_{\gamma_0}} e^{C\mathcal{H}_{\gamma_0}(\gamma_0)t}, t \in [0, T^*), \tag{3.43}$$

and the result follows. □

4. Future directions of research

It would be interesting to consider problem (0.1)-(0.3) with added white noise i.e. to consider problem

$$d\gamma(t) = u^{\gamma(t)}(\gamma(t))dt + \sqrt{2\nu} dw_t, \nu > 0, t \in [0, T] \tag{4.1}$$

$$\gamma(0) = \gamma_0, \tag{4.2}$$

where γ_0 is a geometric ν-rough path, vector field of velocity u^Y is given by (0.2) and w_t is $\mathcal{D}_{\gamma_0}$–valued Wiener process. This model would correspond to Navier-Stokes equations rather than Euler equations. There are two possible mathematical frameworks for the model.

First one is to make change of variables

$$\alpha(t) = \gamma(t) - \sqrt{2\nu} w_t, t \in [0, T].$$

Then we can fix $\{w_t\}_{t\geq 0}$ and system (4.1)-(4.2) is reformulated as follows

$$\frac{d\alpha}{dt} = u^{\alpha(t)+\sqrt{2\nu}w_t}(\alpha(t)+\sqrt{2\nu}w_t), \nu > 0, t \in [0,T] \tag{4.3}$$

$$\alpha(0) = \gamma_0. \tag{4.4}$$

Now the problem (4.3)-(4.4) is ordinary differential equation (ODE) with random coefficients in $\mathcal{D}_{\gamma_0}$ and it can be studied by methods of the theory of random dynamical systems, see [1] and [15]. This approach works only in the case of additive noise.

Second approach is to consider problem (4.1)-(4.2) as SDE in Banach space $\mathcal{D}_{\gamma_0}$. Then, we can consider more general system with multiplicative noise:

$$d\gamma(t) = u^{\gamma(t)}(\gamma(t))dt + \sqrt{2\nu}G(\gamma)dw_t, \nu > 0, t \in [0,T] \tag{4.5}$$

$$\gamma(0) = \gamma_0. \tag{4.6}$$

The problem which appear here is to define Stochastic integral in the Banach space $\mathcal{D}_{\gamma_0}$. Stochastic calculus in M-type 2 Banach spaces developed in works [13]-[14], [8], [10] does not work in this situation. It seems that it is necessary to try to alter definition of $\mathcal{D}_{\gamma_0}$ to be able to apply the theory.

Other possible direction of research is the theory of connections on infinite dimensional manifolds, see [19], [7], [24]. In [9] the authours claimed, see p. 251 therein, that it is possible to define the topological space of Gawędzki's [19] line bundle over the set of rough loops in the sense of Lyons [25]. Since the trajectories of the Brownian loop are almost surely rough paths, this allows us to define the topological space of Gawędzki's line bundle over the Brownian bridge, because it is possible to define the integral of a one-form over a rough path. It would be interesting to write down a complete proof of this claim. The theory presented in this article could be seen as a first step in realizing such a programme.

REFERENCES

[1] Ludwig Arnold, *Random dynamical systems*, Springer Monographs in Mathematics, Springer-Verlag, Berlin, 1998. MR1723992 (2000m:37087)

[2] J. T. Beale, T. Kato, and A. Majda, *Remarks on the breakdown of smooth solutions for the* 3*-D Euler equations*, Comm. Math. Phys. **94** (1984), no. 1, 61–66. MR763762 (85j:35154)

[3] John B. Bell and Daniel L. Marcus, *Vorticity intensification and transition to turbulence in the three-dimensional Euler equations*, Comm. Math. Phys. **147** (1992), no. 2, 371–394. MR1174419 (93c:76048)

[4] Luigi C. Berselli and Hakima Bessaih, *Some results for the line vortex equation*, Nonlinearity **15** (2002), no. 6, 1729–1746, DOI 10.1088/0951-7715/15/6/301. MR1938468 (2003m:76028)

[5] Luigi C. Berselli and Massimiliano Gubinelli, *On the global evolution of vortex filaments, blobs, and small loops in 3D ideal flows*, Comm. Math. Phys. **269** (2007), no. 3, 693–713, DOI 10.1007/s00220-006-0142-x. MR2276358 (2007m:76027)

[6] Hakima Bessaih, Massimiliano Gubinelli, and Francesco Russo, *The evolution of a random vortex filament*, Ann. Probab. **33** (2005), no. 5, 1825–1855, DOI 10.1214/009117905000000323. MR2165581 (2006i:60069)

[7] Jean-Luc Brylinski, *Loop spaces, characteristic classes and geometric quantization*, Progress in Mathematics, vol. 107, Birkhäuser Boston Inc., Boston, MA, 1993. MR1197353 (94b:57030)

[8] Zdzisław Brzeźniak, *Stochastic partial differential equations in M-type* 2 *Banach spaces*, Potential Anal. **4** (1995), no. 1, 1–45, DOI 10.1007/BF01048965. MR1313905 (95m:35213)

[9] Zdzisław Brzeźniak and Remi Léandré, *Horizontal lift of an infinite dimensional diffusion*, Potential Anal. **12** (2000), no. 3, 249–280, DOI 10.1023/A:1008622712051. MR1752854 (2001d:58043)

[10] Zdzisław Brzeźniak, *Some remarks on Itô and Stratonovich integration in 2-smooth Banach spaces*, Probabilistic methods in fluids, World Sci. Publ., River Edge, NJ, 2003, pp. 48–69, DOI 10.1142/9789812703989_0004. MR2083364 (2005g:60085)

[11] Henri Cartan, *Differential calculus*, Hermann, Paris, 1971. Exercises by C. Buttin, F. Rideau and J. L. Verley; Translated from the French.

[12] Alexandre J. Chorin, *Vorticity and turbulence*, Applied Mathematical Sciences, vol. 103, Springer-Verlag, New York, 1994. MR1281384 (95m:76043)

[13] Egbert Dettweiler, *Stochastic integration of Banach space valued functions*, Stochastic Space-Time Models and Limit Theorems (L. Arnold and P. Kotelenez, eds.), Springer, 1985, pp. 33–79.

[14] ———, *Stochastic integration relative to Brownian motion on a general Banach space*, Doğa Mat. **15** (1991), no. 2, 58–97 (English, with Turkish summary). MR1115509 (93b:60112)

[15] Jinqiao Duan, Kening Lu, and Björn Schmalfuss, *Invariant manifolds for stochastic partial differential equations*, Ann. Probab. **31** (2003), no. 4, 2109–2135, DOI 10.1214/aop/1068646380. MR2016614 (2004m:60136)

[16] Peter K. Friz, *Continuity of the Itô-map for Hölder rough paths with applications to the support theorem in Hölder norm*, Probability and partial differential equations in modern applied mathematics, IMA Vol. Math. Appl., vol. 140, Springer, New York, 2005, pp. 117–135, DOI 10.1007/978-0-387-29371-4_8. MR2202036 (2007f:60070)

[17] Peter K. Friz and Nicolas B. Victoir, *Multidimensional stochastic processes as rough paths*, Cambridge Studies in Advanced Mathematics, vol. 120, Cambridge University Press, Cambridge, 2010. Theory and applications. MR2604669 (2012e:60001)

[18] Giovanni Gallavotti, *Foundations of fluid dynamics*, Texts and Monographs in Physics, Springer-Verlag, Berlin, 2002. Translated from the Italian. MR1872661 (2003e:76002)

[19] K. Gawędzki, *Topological actions in two-dimensional quantum field theories*, Nonperturbative quantum field theory (Cargèse, 1987), NATO Adv. Sci. Inst. Ser. B Phys., vol. 185, Plenum, New York, 1988, pp. 101–141. MR1008277 (90i:81122)

[20] M. Gubinelli, *Controlling rough paths*, J. Funct. Anal. **216** (2004), no. 1, 86–140, DOI 10.1016/j.jfa.2004.01.002. MR2091358 (2005k:60169)

[21] M. Hairer, *Rough stochastic PDEs*, Comm. Pure Appl. Math. **64** (2011), no. 11, 1547–1585, DOI 10.1002/cpa.20383. MR2832168

[22] H. Helmholtz, *Über Integrale der hydrodynamischen Gleichungen, welche den Wirbelbewegungen entsprechen.*, Journal für die reine und angewandte Mathematik (Crelles Journal) **1858** (1858), no. 55, 25–55, DOI 10.1515/crll.1858.55.25.

[23] W. Thomson (Lord Kelvin), *On vortex motion*, Trans. Royal Soc. Edin. **25** (1869), 217–260.

[24] Rémi Léandre, *String structure over the Brownian bridge*, J. Math. Phys. **40** (1999), no. 1, 454–479, DOI 10.1063/1.532781. MR1657812 (2000k:58044)

[25] Terry J. Lyons, *Differential equations driven by rough signals*, Rev. Mat. Iberoamericana **14** (1998), no. 2, 215–310, DOI 10.4171/RMI/240. MR1654527 (2000c:60089)

[26] Terry J. Lyons, Michael Caruana, and Thierry Lévy, *Differential equations driven by rough paths*, Lecture Notes in Mathematics, vol. 1908, Springer, Berlin, 2007. Lectures from the 34th Summer School on Probability Theory held in Saint-Flour, July 6–24, 2004; With an introduction concerning the Summer School by Jean Picard. MR2314753 (2009c:60156)

[27] Terry Lyons and Zhongmin Qian, *System control and rough paths*, Oxford Mathematical Monographs, Oxford University Press, Oxford, 2002. Oxford Science Publications. MR2036784 (2005f:93001)

[28] L. Rosenhead, *The Spread of Vorticity in the Wake Behind a Cylinder*, Proceedings of the Royal Society A: Mathematical, Physical and Engineering Sciences **127** (1930), no. 806, 590–612, DOI 10.1098/rspa.1930.0078.

[29] A. and Meneguzzi Vincent M., *The Spatial Structure and Statistical Properties of Homogeneous Turbulence*, Journal of Fluid Mechanics **225** (1991), 1–20, DOI 10.1017/S0022112091001957.

[30] L. C. Young, *An inequality of the Hölder type, connected with Stieltjes integration*, Acta Math. **67** (1936), no. 1, 251–282, DOI 10.1007/BF02401743. MR1555421

†DEPARTMENT OF MATHEMATICS, UNIVERSITY OF YORK, HESLINGTON, UK,
‡CEREMADE & CNRS UMR 7534, UNIVERSITÉ PARIS-DAUPHINE, FRANCE